

# ping200S Control Application

uAvionix Ping200S Control App



The ping200S Control Application allows users to test ping200S functionality by sending commands to the ping200S over RS-232 to from a Windows PC. A serial connection to the ping200S is required.

Cable Assembly: Ping200s can be controlled via serial RS-232 communication by a control head or for testing and development using the provided **Ping20XS Control Application**.

Terminate/solder the COM TX, COM RX and RS232 ground to DB9 connector or appropriate connector for your application/aircraft.

RX

TX

CTS

RI



ping200s Pin	Туре	Physical	RS-232 Pin (typical)
1	Ground		N/A
2	Ground	Unused	N/A
3	Aircraft Power	11-33V	N/A
4	ping200s COM TX	RS232 57600	2 RS-232 RX
5	ping200s COM RX	RS232 57600	3 RS-232 TX
6	RS232 Ground		5

#### Launch

Download the ping200S control application: <a href="http://www.uavionix.com/downloads/ping200s/ping200scontrol/Ping20XSControl.exe">http://www.uavionix.com/downloads/ping200s/ping200scontrol/Ping20XSControl.exe</a>

- 1. Connect ping200s to the PC.
- 2. Power ping200S using the supplied power adapter and battery or an alternative power source. Never power ping200s without an antenna or a 50 ohm load attached to the SMA connector on ping200S.

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- 3. Launch Ping200SControl.exe.
- 4. Select the correct COM port.
- 5. Select 57600 for the App Baud.
- 6. Select the desired protocol. An explanation of each setting can be found on the following pages.
- 7. Click Start
- 8. The Control Status at the bottom left of the application should change to Started. Ping200S Ownship data should populate the Ownship portion of the application.
- 9. Changes can be made to the ping200S through the application. When the checkbox is toggled the changes in the adjacent fields are sent live to the ping200S.
- 10. Changes will be visible in the ownship display area of the application.

### **GDL90 Settings**

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File							
COM Settin	gs						-
Port	COM1		~			. 6	3
App Baud	p Baud 57600		~		uAvioni		
Protocol	GDL9	0	~	Ownship Display		Pkts:	
GDL90 Cor	trol Sett	ings		Lattitude:		Ens:	
Callsign		PING		Baro Altitude:			
Mode	$\square$	STBY	~	Horizontal Velocity:		U	
Squawk		1200	-	Heading: Vertical Velocity			
Emergency	NON	E	~	Emergency Code:			
	8	Healthy		NACp: Emitter Category:			
	-			The second s	9	IDENT	
					10	Start	
Control Statu	s: Ston	ped					

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- 1. COM Port: Select the appropriate port for 200s.
- 2. App Baud: Serial Baud rate, select the default value of 57600.
- 3. Protocol: Select the desired communication protocol.
- 4. Flight ID: Enter the assigned Flight ID. Check the box to send the bit to the transponder.
- 5. Mode: Select the transponder operating mode. Available modes: Off, Stby, On, Alt.
- 6. Squawk: 4 digit squawk codes. Entering an emergency code such as 7700 will, cause the appropriate emergency bit to be set automatically.
- 7. Emergency: Select an emergency code. Changes to this field will not auto populate the Squawk code.
- 8. Healthy: Sets the Healthy bit On or Off
- 9. Ident: Sets the transponder to Ident for an 18 second interval.
- 10. Start: Start application control of the Transponder.
- **11. Ownship Display:** Displays the current transponder and position information.

## SageTech Settings



Ping20X	SControl	v1.0			-		×
File							
COM Settin	igs						
Port	COM1 ~ 57600 ~		$\sim$			. (	5
App Baud			~		UAVIONI		
Protocol	SageTe	ech	~	Ownship Display		Pkts:	
SageTech	Control S	ettings		Lattitude:		Ens:	
Callsign		PING		Baro Altitude: GNSS Altitude:	U		
Squawk		1200	-	Horizontal Velocity:			
Mode	[	STANDBY	~	Vertical Velocity: Emergency Code			
Altitude		0	-	NIC:			
	1.5			Emitter Category:			
					8	IDENT	
					9	Start	

- 1. COM Port: Select the appropriate port for 200s.
- 2. App Baud: Serial Baud rate, select the default value of 57600.
- 3. **Protocol:** Select the desired communication protocol.
- 4. Flight ID: Enter the assigned Flight ID. Check the box to send the bit to the transponder.
- 5. Squawk: 4 digit squawk codes are entered here. Entering an emergency code such as 7700 will, cause the appropriate emergency bit to be set automatically.
- 6. Mode: Select the transponder operating mode. Available modes: Off, Stby, On, Alt.
- 7. Altitude: Specify an altitude for all barometric altitude broadcasts.
- 8. Ident: Sets the transponder to Ident for an 18 second interval.
- 9. Start: Start application control of the Transponder.
- **10. Ownship Display:** Displays the current transponder and position information.

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