



# ping2020i

**uAvionix Ping2020i Transceiver**

**QUICK START GUIDE**

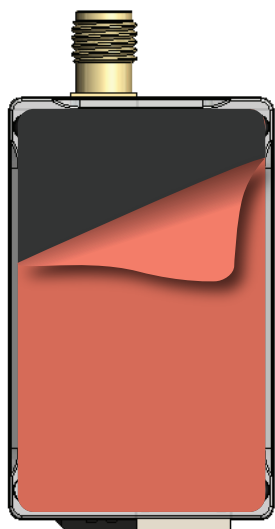
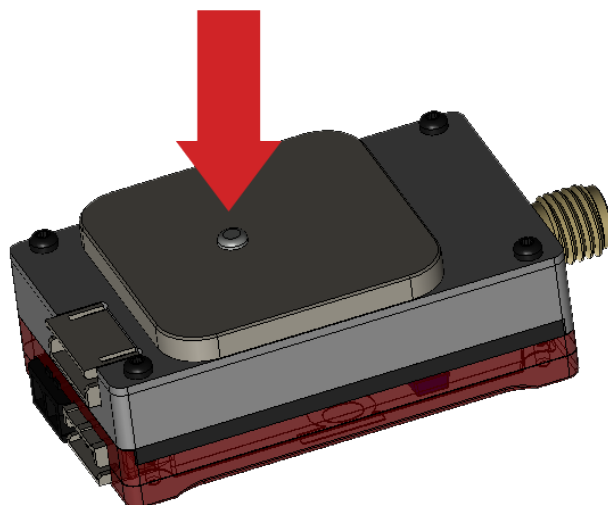


# Mount

# 1

The ping2020i GPS antenna requires a clear view of the sky for proper operation. Avoid placing the device directly under props or near features that could 'shadow' or block the GPS antenna during flight. Avoid installing the ping2020i under any signal blocking materials such as carbon fiber.

GPS Antenna



Prior to mounting confirm all cable lengths will be sufficient to reach a power source.

**Mount ping2020i** to a suitable flat surface using the provided **double-sided mounting tape**. Affix mounting tape to the ping logo side of the transceiver and secure to the aircraft.

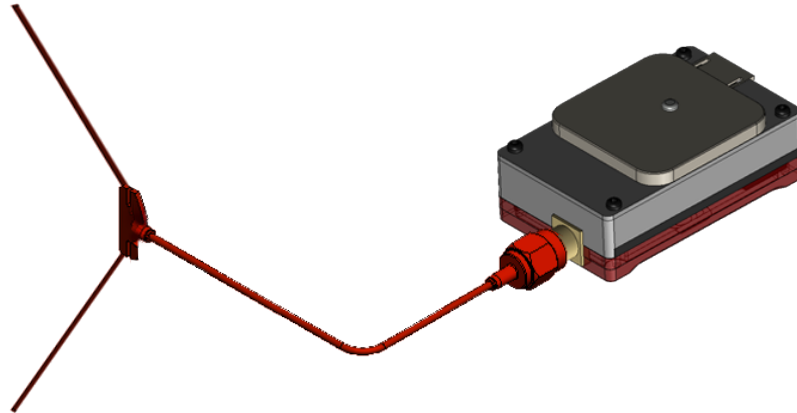


# Connect

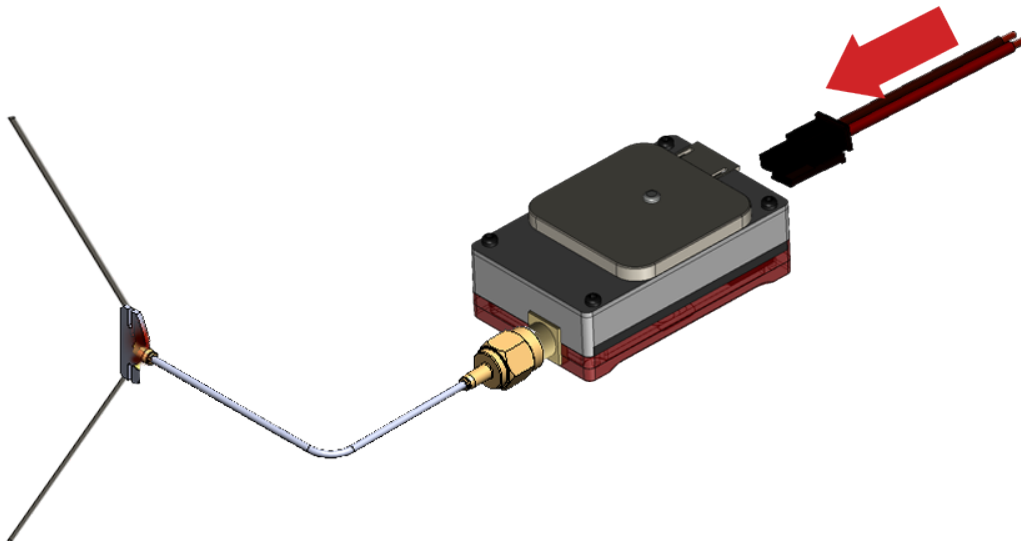
# 2

**Connect the antenna to ping2020i** The antenna should be mounted in a vertical orientation using the provided double sided mounting foam.

Place the antenna in a location that will be least obstructed by the aircraft during normal flight.



**Connect power harness** to ping2020i. Connect the free end of the harness to a 3S battery or appropriate aircraft power source.

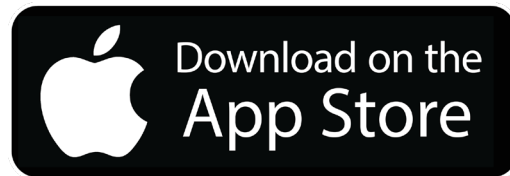




# Install

# 3

Install the uAvionix Ping App from the Apple App Store or Google Play. Search for **uAvionix Ping Installer** or use the QR codes below.



Connect the **ping Programmer** to **ping2020i** using the provided **JST ZHR-5-4 pin cable**. The 5 pin connector should be connected to the transceiver. The 4 pin should be connected to the **ping Programmer**.

Apply 11-28V DC to the **ping2020i**.





# Join

# 4

Join your mobile device to the wireless network named **Ping-XXXX** using the procedure for your device. If a WPA passphrase is required enter **uavionix**. The process for iOS is shown below.

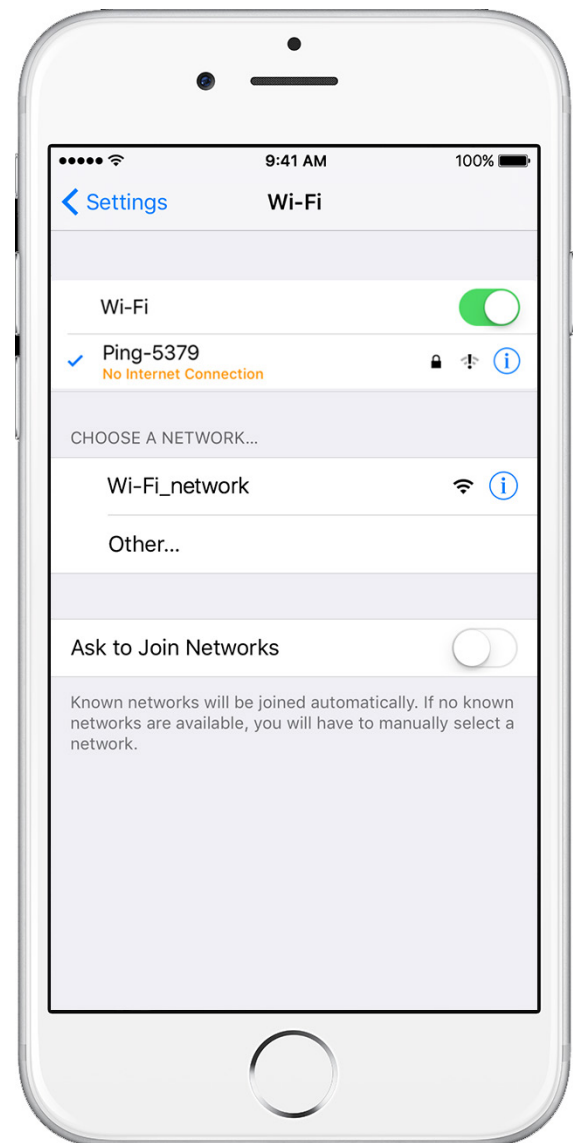
Go to **Settings > Wi-Fi**, and verify Wi-Fi is turned on.

Tap the SSID **Ping-XXXX**, where XXXX is a random string i.e. Ping-5379.

Enter **uavionix** as the WPA password, if required for the network, then tap **Join**

**Note:** *No Internet Connection* message is normal.

After device is connected proceed to step 5.





# Configure

# 5

Launch the **uAvionix Ping** application and complete the fields as required for your device/aircraft.

**Selected Device Type:** Choose Ping2020

**Control:** This setting controls device transmit functions. The selections available will depend on the device type selected.

Transceiver selections include:

**TX enabled:** Transmit ADS-B message at one second intervals, receive is also enabled.

**Receive:** Receive only, transmit disabled.

**Standby:** ADS-B in/out disabled.

**ICAO:** Enter your ICAO Number in Hexadecimal format. If your identifier is in octal (eight digits) format you must convert it prior to entry.

**Call Sign:** Enter the tail number of the aircraft. (A-Z 0-9)

**Emitter:** This should be set to your aircraft type. UAV is the selection for unmanned vehicles.

**V<sub>50</sub>:** Enter airspeed in knots that the aircraft typically flies at after takeoff. Default value (1)

**Aircraft Length:** Select the length value in meters that matches your aircraft.

**Aircraft Width:** Select the width value in meters that matches your aircraft.

**GPS Antenna Offsets:** Choose the lateral and longitudinal offset in meters from GPS to the nose of your aircraft.

The screenshot shows the configuration interface of the uAvionix Ping application. At the top, the 'ping' logo is displayed in red and grey. Below it, a green status bar indicates 'CONNECTED TO DEVICE'. Two tabs are visible: 'Configuration' (active) and 'Monitor'. The configuration section includes the following fields:

- Selected Device Type:** A dropdown menu set to 'ping2020'.
- Control:** A dropdown menu set to 'UAT TX enabled'.
- ICAO Number (hex):** A text input field with the example 'e.g. 012ABC'.
- Call Sign:** A text input field with the example 'e.g. N12345'.
- Emitter Category:** A dropdown menu set to 'UAV'.
- V<sub>50</sub> (knots):** A text input field with the value '1'.
- Aircraft Length (meters):** A dropdown menu set to 'L ≤ 15'.
- Aircraft Width (meters):** A dropdown menu set to 'W ≤ 23'.
- GPS Antenna Offset, Lateral from roll axis (meters):** A text input field with the value '0'.
- Antenna Offset, Longitudinal aft from aircraft nose (meters):** A text input field with the value '0'.

At the bottom of the configuration section is a green 'Update' button.



# Update

# 6

After completing all data fields tap the **Update** button.

You should receive the **Device Configured** message, tap **OK**.

Tap **Monitor**.

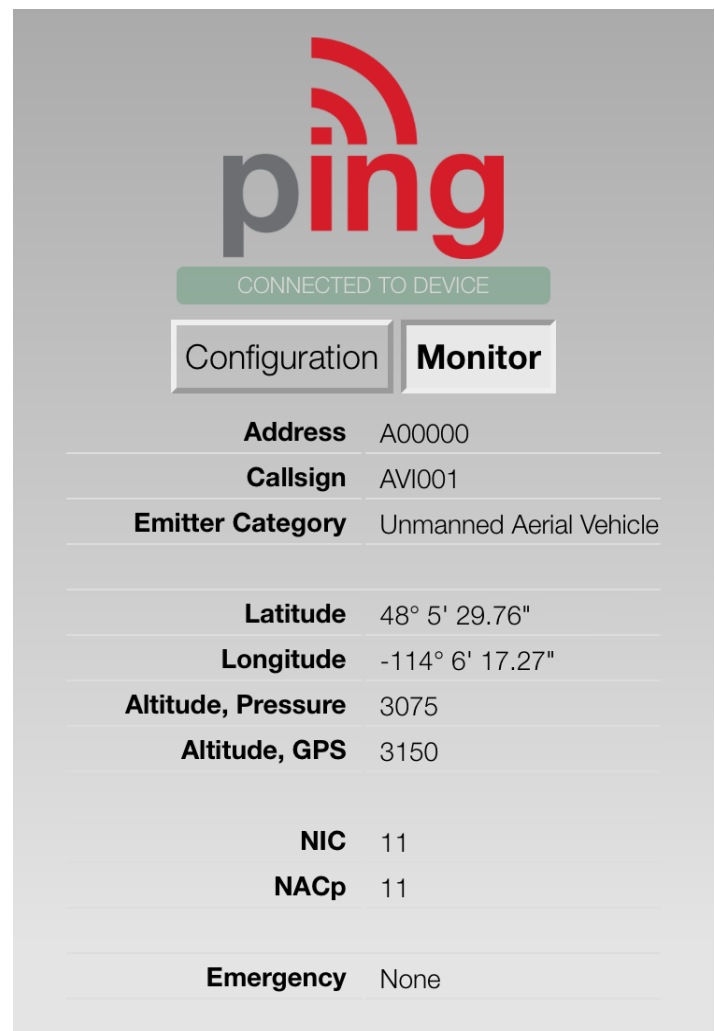
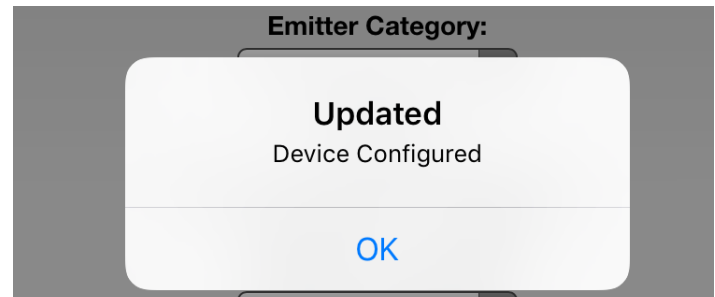
**Verify** all fields are correct for your aircraft.

A GPS fix is not necessary for programming but is required to monitor latitude longitude and GPS altitude.

**Disconnect** power from **ping2020i**

**Disconnect ping Programmer from ping2020i.**

**ping2020i** will not transmit if the **ping Programmer** is attached.



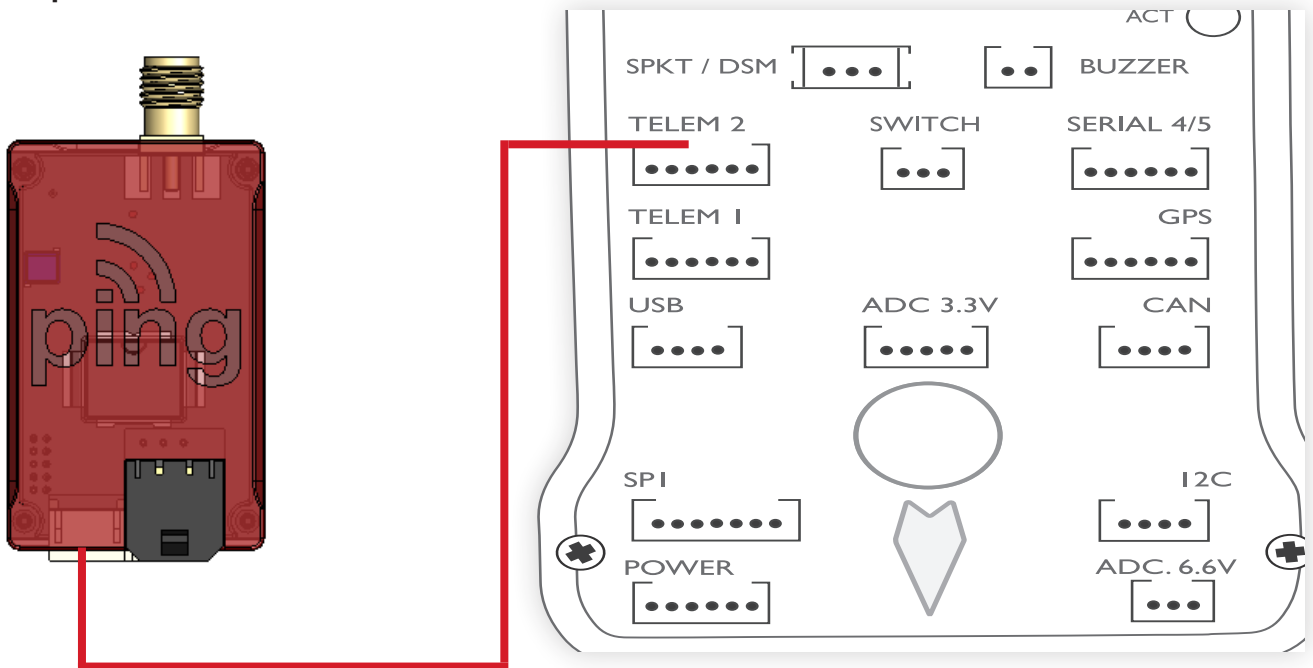


# Connect Pixhawk (optional)

# 7

The received ADS-B data can optionally be sent to an autopilot or ground station. Configuration is autopilot dependent, minimal setup for Pixhawk is shown below.

Connect the provided cable to the 4 pin JST port on the ping transceiver. Plug remaining 6 pin DF13 serial cable connector into TELEM2 port of Pixhawk.



Connect to your Pixhawk Autopilot using Mission Planner.  
Set the ADSB\_ENABLE parameter to 1.

When ADS-B traffic is received the green LED will flash and the traffic should appear on the Mission Planner map.

For a full list of available Ardupilot parameters visit <http://ardupilot.org/>

For additional support: [uavionix.com/support](http://uavionix.com/support)

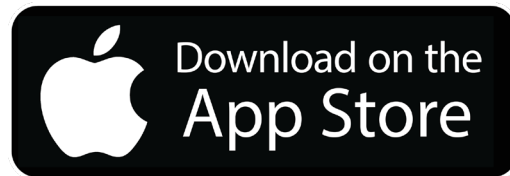




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