

uAvionix truFYX NMEA ICD

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300 Pine Needle Lane

Bigfork, MT 59911

http://www.uavionix.com

support@uavionix.com

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1 Revision History

| Revision | Date | Comments | |
|----------|------------|--|--|
| Α | 6/15/2018 | Initial release | |
| В | 6/21/2018 | Add PUAVVER, PUAVOK, PUAVERR sentences | |
| С | 7/9/2018 | Add PUAVALT sentence | |
| D | 8/31/2018 | Changed defaults | |
| E | 10/29/2018 | PUAVVV sentences | |
| F | 12/3/2018 | PUAVSTAT sentence | |
| G | 12/4/2018 | Add uptime to PUAVSTAT sentence | |
| Н | 12/26/2018 | Add PUAVCFG sentence, enable PUAVNOM persistence, add PUAVRST factory reset | |
| I | 2/8/2019 | Add TSO-145d/e compliance option to PUAVCFG and expand SBAS PRN Identifiers | |
| J | 3/29/2019 | Add heater control to PUAVCFG and require checksum for PUAVCFG, PUAVNOM and PUAVRST commands Add NMEA 0183 sentence details Clarify electrical specification | |
| K | 4/26/2019 | Rename document from "pingGNSS NMEA ICD" to "truFYX NMEA ICD" | |
| L | 10/10/2019 | Add "Signal ID" field to GPGSV sentence | |
| M | 4/9/2020 | Add part number to PUAVVER sentence | |
| N | 2/17/2021 | Add option to PUAVRST and periodic output of PUAVVER | |

2 Introduction

This document describes the uAvionix truFYX NMEA data interface implementation. The interface is an adaptation of and extension to the NMEA 0183 Interface Standard.

2.1 NMEA 0183

truFYX NMEA sentences are based on the NMEA 0183 interface standard (Version 4.10). The NMEA 0183 standard can be found here:

https://www.nmea.org/content/STANDARDS/NMEA_0183_Standard

2.2 Electrical Interface

NMEA 0183 is a combined electrical and data specification. The truFYX NMEA interface does not adhere to the NMEA 0183 electrical specification. The truFYX device instead communicates over serial with the following line characteristics:

Rate: 115,200 bps

Data Length: 8 bits
Parity: None
Stop Bits: 1 bit
Flow Control: None

Signal Level: Device specific (TTL or RS-232)

2.3 Data Interface

NMEA uses ASCII data transmitted in sentences. Refer to the NMEA 0183 standard for more information on structure, including delimiters and checksums.

Data is bidirectional.

Sentences are nominally transmitted at 5 Hz, although some sentences may be noted as being transmitted at different rates.

2.4 PRN Identifiers

Satellite PRN identifiers used in NMEA sentences are as follows:

- GPS from 1 to 32
- SBAS from 33 to 70

2.5 Sentences

The following sentence is transmitted at startup:

PUAVVER

By default, the following sentences are transmitted during normal operation, in this order:

GPRMC

- GPGGA
- GPGSA
- GPGSV
- GPGLL
- GPVTG
- GPZDA
- RAIM
- PUAVALT
- PUAVVV
- PUAVVER

The following sentences are not transmitted by default:

- PUAVSBMC
- PUAVPRM
- PUAVSTAT

The PUAVNOM message can be used to adjust the output NMEA sentence mask. By default, adjusting the output sentence mask is volatile, and the mask will be reset after device power cycle.

2.5.1 **GPRMC**

Description: Recommended minimum specific GPS data

Rate: 5 Hz

Direction: Device to host

Example:

\$GPRMC,214821.00,A,4158.37295,N,08741.37695,W,0.271,109.44,291116,0.0,E,D,V*62

| Field | Definition | | |
|---------------------|---|--|--|
| Timestamp | UTC time of position fix, hhmmss.ss | | |
| Status | A = Data valid | | |
| | V = Navigation receiver warning | | |
| Latitude | Latitude in degrees, DDMM.MMMMM | | |
| Latitude Direction | N = North | | |
| | S = South | | |
| Longitude | Longitude in degrees, DDDMM.MMMMM | | |
| Longitude Direction | E = East | | |
| | W = West | | |
| Velocity | Velocity over ground, knots | | |
| Course | Course over ground, degrees true | | |
| Date | Date of position fix, ddmmyy | | |
| Magnetic Variation | Magnetic variation, degrees | | |
| | Note: Not currently implemented – returns 0.0 | | |
| Magnetic Variation | E = East | | |
| Direction | W = West | | |

| | Note: Not currently implemented – returns E |
|------|--|
| Mode | Positioning system mode |
| | N = No fix |
| | A = Autonomous, non-differential mode position fix |
| | D = Differential mode position fix (SBAS) |

2.5.2 **GPGGA**

Description: GPS fix data

Rate: 5 Hz

Direction: Device to host

Example:

\$GPGGA,214821.00,4158.37295,N,08741.37695,W,2,08,1.0,186.24,M,,M,,*59

| Field | Definition | | | |
|---------------------|---|--|--|--|
| Timestamp | UTC time of position fix, hhmmss.ss | | | |
| Latitude | Latitude in degrees, DDMM.MMMMM | | | |
| Latitude Direction | N = North | | | |
| | S = South | | | |
| Longitude | Longitude in degrees, DDDMM.MMMMM | | | |
| Longitude Direction | E = East | | | |
| | W = West | | | |
| GPS Quality | 0 = No fix | | | |
| | 1 = GPS | | | |
| | 2 = Differential GPS | | | |
| Satellites in Use | Number of satellites in use | | | |
| HDOP | Horizontal Dilution of Precision | | | |
| Altitude | Height above ellipsoid | | | |
| | Note: Height above geoid not provided | | | |
| Altitude Units | M = Meters | | | |
| Geoidal Separation | Geoidal separation | | | |
| | Note: Not currently implemented – returns 0.0 | | | |
| Geoidal Separation | M = Meters | | | |
| Units | | | | |
| Differential Age | Age of differential data | | | |
| | Note: Not currently implemented – returns empty | | | |
| Differential | Differential reference station ID | | | |
| Reference | Note: Not currently implemented – returns empty | | | |

2.5.3 GPGSA

Description: GPS DOP and active satellites

Rate: 5 Hz

Direction: Device to host

Example:

UAV-1002084-001

Rev N

7

\$GPGSA,A,3,14,18,12,25,31,10,32,24,,,,1.71,0.96,1.42,1*1C

| Field | Definition |
|----------------------|--|
| Mode | M = Manual |
| | A = Auto 2D/3D |
| Current Mode | 1 = No fix |
| | 2 = 2D |
| | 3 = 3D |
| Satellite PRNs [112] | List of satellite PRNs used in position fix, maximum of 12 |
| PDOP | Position Dilution of Precision |
| HDOP | Horizontal Dilution of Precision |
| VDOP | Vertical Dilution of Precision |

2.5.4 GPGSV

Description: GPS satellites in view

Note: Satellite information may require the transmission of multiple sentences

Rate: 5 Hz

Direction: Device to host

Example:

\$GPGSV,3,1,10,32,73,346,35,10,67,128,40,14,56,284,30,31,36,206,40,0*7B \$GPGSV,3,2,10,18,35,131,35,25,25,117,23,12,24,074,34,01,19,317,0,*78 \$GPGSV,3,3,10,11,17,296,23,24,13,044,22,,,,,,,0*76

| Field | Definition | | |
|----------------------------|--|--|--|
| Total Sentences | Total number of sentences, 1 to 9 | | |
| Sentence Number | This sentence number, 1 to 9 | | |
| Satellites in View | Total number of satellites in view | | |
| Satellite X [15] PRN | PRN of satellite X | | |
| Satellite X [15] Elevation | Elevation of satellite X, degrees | | |
| Satellite X [15] Azimuth | Azimuth of satellite X, degrees true | | |
| Satellite X [15] C/N0 | Carrier to Noise Ratio of satellite X, dB-Hz | | |
| Signal ID | 0 = All Signals | | |
| | 1 = L1 C/A | | |
| | 2 = L1 P(Y) | | |
| | 3 = LA M | | |
| | 4 = L2 P(Y) | | |
| | 5 = L2C-M | | |
| | 6 = L2C-L | | |
| | 7 = L5-l | | |
| | 8 = L5-Q | | |
| | 9-F = Reserved | | |

2.5.5 **GPGLL**

Description: Geographic position, latitude/longitude and time

Rate: 5 Hz

Direction: Device to host

Example:

\$GPGLL,4158.37295,N,08741.37695,W,214821.00,A,D*74

| Field | Definition |
|---------------------|--|
| Latitude | Latitude in degrees, DDMM.MMMMM |
| Latitude Direction | N = North |
| | S = South |
| Longitude | Longitude in degrees, DDDMM.MMMMM |
| Longitude Direction | E = East |
| | W = West |
| Timestamp | UTC time of position fix, hhmmss.ss |
| Status | A = Data valid |
| | V = Data not valid |
| Mode | Positioning system mode |
| | N = No fix |
| | A = Autonomous, non-differential mode position fix |
| | D = Differential mode position fix (SBAS) |

2.5.6 **GPVTG**

Description: Track made good and ground speed

Rate: 5 Hz

Direction: Device to host

Example:

\$GPVTG,109.44,T,,M,0.271,N,0.502,K,D*33

| Field | Definition |
|----------------------------|--|
| Course, True | True course over ground, degrees |
| Course, True Reference | T = True |
| Course, Magnetic | Magnetic course over ground, degrees |
| - | Note: Not currently implemented – returns empty |
| Course, Magnetic Reference | M = Magnetic |
| Velocity, Knots | Velocity over ground, knots |
| Velocity, Knots Units | N = Knots |
| Velocity, km/h | Velocity over ground, kilometers per hour |
| Velocity, km/h Units | K = kilometers per hour |
| Mode Indicator | N = No fix |
| | A = Autonomous, non-differential mode position fix |
| | D = Differential mode position fix (SBAS) |

2.5.7 **GPZDA**

Description: UTC time and date

UAV-1002084-001

Rev N

Rate: 5Hz

Direction: Device to host

Example:

\$GPZDA,214821.00,29,11,2016,,*64

| Field | Definition |
|--------------------|---|
| Timestamp | UTC time of position fix, hhmmss.ss |
| Day | Day of month (1 to 31) |
| Month | Month (1 to 12) |
| Year | Year |
| Local Zone Hours | Note: Not currently implemented – returns empty |
| Local Zone Minutes | Note: Not currently implemented – returns empty |

2.5.8 **RAIM**

Description: Protection limits, figures of merit, and uncertainty

Rate: 5 Hz

Direction: Device to host

Example:

\$RAIM,016933,009032,003383,000939,048034,013294,000000,000000,010,5,00111111*37

| Field | Definition | | | | | | |
|----------|--|------------------|---------------|--------------|---------|-----|-----|
| HPL | 6 digits of Horizontal Protection Limit, cm | | | | | | |
| VPL | 6 digits of Vertice | cal Protection | Limit, cm | | | | |
| HFOM | 6 digits of Horiz | ontal Figure o | of Merit, cm | | | | |
| VFOM | 6 digits of Vertice | cal Figure of N | /lerit, cm | | | | |
| VHFOM | 6 digits of Veloc | city Horizontal | Figure of N | Merit, m/s | * 10000 | | |
| VVFOM | 6 digits of Veloc | city Vertical Fi | gure of Me | rit, m/s * 1 | 0000 | | |
| HUL | 6 digits of Horiz | ontal Uncerta | inty Limit, o | m | | | |
| | Note: Not curre | ntly implemer | nted – retur | ns 000000 |) | | |
| VUL | 6 digits of Verti | | | | | | |
| | Note: Not currently implemented – returns 000000 | | | | | | |
| Version | 3 digits of Version Number | | | | | | |
| State | Nav State | | | | | | |
| | 0 = Invalid | | | | | | |
| | 2 = 2D | | | | | | |
| | 3 = 3D | | | | | | |
| | 4 = RAIM (with barometric aiding) | | | | | | |
| | 5 = RAIM (without barometric aiding) | | | | | | |
| Validity | 8 digits of data Validity Flags | | | | | | |
| Flags | 7 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | VUL HUL | VVFOM | VHFOM | VFOM | HFOM | VPL | HPL |

2.5.9 PUAVSBMC

Description: SBAS message counts

Note: Not enabled by default

Rate: 5 Hz for each tracked SBAS satellite

Direction: Device to host

Example:

\$PUAVSBMC,133,4,1,0,3,4,0,0,0,1,0,0,0,3,2,0,2,20*3E

| Field | Definition |
|-------|-----------------------------------|
| PRN | Satellite PRN |
| MT0 | Count of MT0 subframes received |
| MT1 | Count of MT1 subframes received |
| MT2 | Count of MT2 subframes received |
| MT3 | Count of MT3 subframes received |
| MT4 | Count of MT4 subframes received |
| MT5 | Count of MT5 subframes received |
| MT6 | Count of MT6 subframes received |
| MT7 | Count of MT7 subframes received |
| MT9 | Count of MT9 subframes received |
| MT17 | Count of MT17 subframes received |
| MT18 | Count of MT18 subframes received |
| MT24 | Count of MT24 subframes received |
| MT25 | Count of MT25 subframes received |
| MT26 | Count of MT26 subframes received |
| MT27 | Count of MT27 subframes received |
| MT28 | Count of MT28 subframes received |
| Total | Count of total subframes received |

2.5.10 PUAVPRM

Description: Pseudorange and observable data

Note: Not enabled by default

Rate: 5 Hz for each tracked satellite

Direction: Device to host

Example:

\$PUAVPRM,17,17802342.971858,93551879.058097,-215.698227,40*4B

| Field | Definition |
|-------------|-----------------------|
| PRN | Satellite PRN |
| Pseudorange | Pseudorange, m |
| Carrier | Carrier phase, cycles |
| Phase | |

| Doppler | Doppler, Hz |
|---------|--|
| CN0 | Carrier to noise ratio (C/N ₀), dBHz |

2.5.11 PUAVNOM

Description: NMEA Output Messages

Sets NMEA output message mask (persistent or non-persistent)

NMEA checksum required on host to device sentence with parameters

Responds with PUAVNOM or PUAVERR

Direction: Host to device

Example: Enable RMC, GGA, GSA, GSV, GLL, VTG, ZDA, and RAIM, non-persistently

Read Configuration

[TX] \$PUAVNOM

[RX] \$PUAVNOM,00000CFF*01

Write Configuration (non-persistent)

[TX] \$PUAVNOM,000000FF*72

[RX] \$PUAVNOM,000000FF*72

Write Configuration (persistent)

[TX] \$PUAVNOM,000000FF,1*6F

[RX] \$PUAVNOM,000000FF*72

| Field | Definition | | | | | | | | |
|---------------|--|----------|-------|-------|-------|-------|-------|-------|-------|
| Mask | 32-bit bitwise selection of enabled messages, transmitted in hex MSB first | | | | first | | | | |
| | | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| | | Dit 1 | Dit 0 | טונ ט | DIL 4 | טונ ט | Dit Z | DIL | Dit 0 |
| | Byte 3 | | | | Rese | erved | | | |
| | | | | | | | | | |
| | | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| | Byte 2 | Reserved | | | | | | | |
| | | • | | | | | | | |
| | | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| | Byte 1 | Rese | erved | VER | STAT | VV | ALT | PRM | SBMC |
| | | | | | | | | | |
| | | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| | Byte 0 | RAIM | ZDA | VTG | GLL | GSV | GSA | GGA | RMC |
| Persist | 0 = Do not persist, reset on power-cycle (default) | | | | | | | | |
| Configuration | 1 = Persist | | | | | | | | |

2.5.12 **PUAVRST**

Description: Reset receiver

Performs receiver reset, clearing data as appropriate

NMEA checksum required on host to device sentence with parameters

Responds with PUAVOK

Direction: Host to device

Example: Warm start

[TX] \$PUAVRST,W*3C

[TX] \$PUAVOK*16

| Field | Definition |
|------------|---|
| Reset Type | W = Warm Start (reset ephemeris, ionospheric, and SBAS corrections) C = Cold Start (reset position, almanac, ephemeris, ionospheric, and SBAS |
| | corrections) F = Factory Reset (do not perform without understanding implications of doing |
| | so) U = Update (reset to bootloader) |

2.5.13 PUAVVER

Description: Version information

NMEA checksum optional on host to device sentence

Rate: One shot on startup, every 60 seconds and in response to \$PUAVVER

Direction: Device to host and host to device

Example:

[TX] \$PUAVVER

[RX] \$PUAVVER,01,03,01,0038,0021,7928A5AE,UAV-1002029-006*4C

| Field | Definition |
|----------------|--|
| FW Major | Firmware Version Major (2 digits decimal) |
| FW Minor | Firmware Version Minor (2 digits decimal) |
| FW Build | Firmware Version Build (2 digits decimal) |
| FW ID | Firmware Identifier (4 digit hex) |
| HW ID | Hardware Identifier (4 digit hex) |
| CRC | Application CRC (8 digits hex) |
| FW Part Number | Firmware Part Number (only available in firmware version 1.3.3 and |
| | greater) |

2.5.14 **PUAVOK**

Description: Input command accepted

Direction: Device to host

Example:

\$PUAVOK*16

2.5.15 PUAVERR

Description: Input command error

Direction: Device to host

Example:

\$PUAVERR*57

2.5.16 **PUAVALT**

Description: Barometric pressure altitude data

Rate: 5 Hz

Direction: Device to host

Example:

\$PUAVALT,902.486267,34.292629,965.346741*41

| Field | Definition |
|-------------|--|
| Pressure | Barometric pressure, mbar |
| Temperature | Temperature, °C |
| Pressure | Pressure altitude at 1013.25 mbar or 29.92 inHg (meters) |
| Altitude | |

2.5.17 **PUAVVV**

Description: Vertical velocity data

Rate: 5 Hz

Direction: Device to host

Example:

\$PUAVVV,2.54,*0F

| Field | Definition |
|-------------------|---|
| Geometric | Geometric vertical velocity, positive when altitude increasing, m/s |
| vertical velocity | |
| Barometric | Barometric vertical velocity (if available), positive when altitude increasing, |
| vertical velocity | m/s |

2.5.18 PUAVSTAT

Description: Status

Rate: 5 Hz

Direction: Device to host

Example:

\$PUAVSTAT,34.3,0,854*3F

| Field | Definition |
|--------------|------------------------------------|
| Temperature | Device temperature, °C |
| | Blank if not available |
| Heater State | 0=Disabled, 1=Enabled (below -20C) |
| Uptime | Device uptime, sec |

2.5.19 PUAVCFG

Description: Device configuration

Reads or sets persistent device configuration information

Provide no parameters to read current configuration

Provide values only for fields to be written

NMEA checksum required on host to device sentence with parameters

Rate: In response to \$PUAVCFG

Direction: Device to host and host to device

Example:

Read Configuration

[TX] \$PUAVCFG

[RX] \$PUAVCFG,N,M,5.0,0,1,0021,D,1*0F

Write Configuration (set elevation mask to 10.0 degrees and disable SBAS ranging)

[TX] \$PUAVCFG,,,10.0,,0*53

[RX] \$PUAVCFG,N,M,10.0,0,0,0021,D,1*3A

| Field | Definition |
|-----------|---|
| COM1 TX | N = NMEA (default) |
| Protocol | M = MAVLink |
| COM2 TX | N = NMEA |
| Protocol | M = MAVLink (default) |
| Elevation | Elevation mask in degrees (default 5.0) |
| Mask | |

| Min CN0 | Minimum CN0 in integer dB-Hz (default 0) |
|------------|--|
| SBAS | 0=Disabled, 1=Enabled (default 1) |
| Ranging | |
| HW ID | Hardware ID, up to 4 hex digits |
| TSO-145 | D = TSO-145d |
| Compliance | E = TSO-145e (default) |
| Heater | 0=Disabled, 1=Enabled (default 1) |